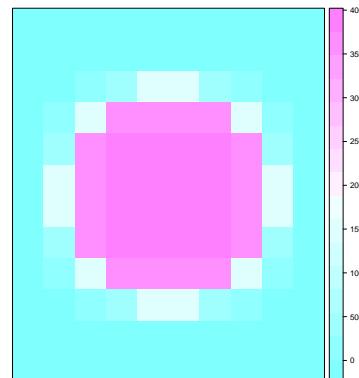


- observations are measured with error
- if obs. are spatially correlated, nearby obs. contain information relevant to the true value / prediction for this obs.
- $\Rightarrow$  predict  $Y_i$  incorporating nearby obs.
- Nearby sometimes means "all", i.e. global mean
- Will talk about concepts with some details
  - Naturally leads to Bayesian inference, won't go that far in 406
- Bivand's example is disease mapping (Chapter 10)
- applies to count data for many outcomes
- We focus on normally distributed outcomes

## Spatial smoothing

- Made up map of # cases of flu in central Iowa in January 2013
- Picture on next two slides
  - expressed as # cases / person
  - Overall rate in February expected to be similar to that observed in January
- Q: Where do you expect February rate to be the highest?
- it may help to know that # people large in middle, small at edges

## "flu" data: sample size per area



## "flu" data: empirical proportion of cases per area



- Made up map of # cases of flu in central Iowa in January 2013
  - expressed as # cases / person
  - Rate in February expected to be similar to that observed in January
- Q: Where do you expect February rate to be the highest?
- A: Not one of the red areas on the edge !!

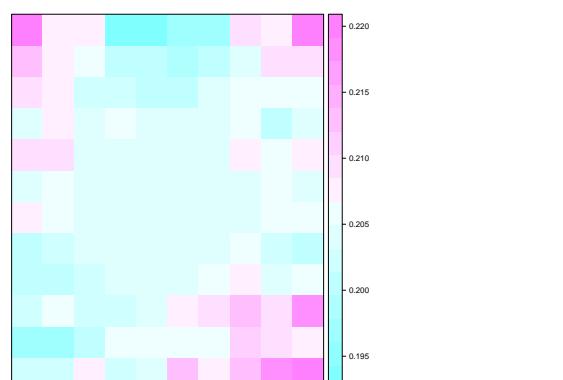
## Spatial Smoothing

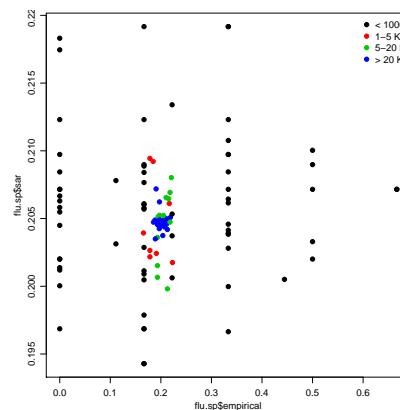
- Why an unusually large value on edge of map may be noise, not signal
  - often a consequence of sample size
  - each square in the middle is ca 10,000 people. Those on the edges are ca 100
  - e.g. big city in the middle of the mapped area
- sd of estimated rate 10x higher in edge squares.
- if assume rates are spatially correlated, nearby areas inform about poorly est. areas, especially if nearby areas have large N
- Another difference between areal and geostatistical data
  - Geostat: Often reasonable to assume constant variance
  - Areal: Often not.
  - Var, or sd, depends on something else about each region (e.g. N)

## Smoothing using SAR or CAR models

- The CAR and SAR models in the previous section performed spatial smoothing
- Two types of predictions
  - ignoring neighbor values: prediction using only fixed effect part of the model
  - including neighbor values: fixed effect + sum of neighbor contributions
- Plot of 2nd on next two slides
- Predictions smoothed to overall mean because large values usually surrounded by smaller values
  - Average of neighboring residuals close to 0

## "flu" data: SAR predictions





## Spatial smoothing

- Why something new?
  - Var  $Y_i$  not constant in a CAR or SAR model
    - depended on neighbor structure
    - not on anything else
    - the independent  $\nu_i$  had constant variance
  - In many applications
    - Small area estimation of survey data
    - Disease mapping
  - Var  $Y_i$  depends on additional features of location  $i$

## Role of sample size

- Often the sample size
- When  $Y_i$  for a location is an average of  $N_i$  responses
- When modeling disease prevalence
  - $Y_i = D_i/N_i$ , number of disease cases / population
  - Var  $Y_i \propto 1/N_i$
- Larger  $N_i \Rightarrow$  smaller variance
- amount of smoothing depends on sample size
  - when  $N_i$  large: little smoothing,  $\hat{\mu}_i$  close to  $Y_i$
  - when  $N_i$  small: want to smooth a lot
- Need to allow Var  $Y_i$  to depend on something we specify

## Smoothing areal data

- Will keep things simple to emphasize concepts
  - Observe  $Y_i$  in a region, have multiple regions
  - Believe that each  $Y_i$  observed with some random error
  - Want to predict "true"  $\mu_i$  for each region
    - Normally distributed observations
- $$Y_i \sim N(\mu_i, \sigma^2)$$
- assume (to keep things simple) that  $\sigma^2$  known
  - $\sigma^2$  may be different for each region
- Statistical problem:
    - Given  $Y_i$  predict  $\mu_i$
  - Two common ways to solve:
    - mixed model:  $Y_i = \mu + \alpha_i + \varepsilon_i$ ,  $\alpha_i \sim N(0, \sigma_a^2)$ ,  $\varepsilon_i \sim N(0, \sigma_e^2)$   
Find BLUP of  $\alpha_i$
    - Bayes:  $Y_i \sim N(\mu_i, \sigma^2)$ , find posterior distribution of  $\mu_i | Y_i$

## Smoothing areal data using a mixed model

- model:  $Y_i = \mu + \alpha_i + \varepsilon_i$ ,  $\alpha_i \sim N(0, \sigma_a^2)$ ,  $\varepsilon_i \sim N(0, \sigma_e^2)$
- $\mu$ : fixed constant,  $\alpha_i$  and  $\varepsilon_i$  are random effects
- Interpretation of the two random effects:
  - $\varepsilon_i$ : measurement error, not repeatable, not part of "true" region-specific  $\mu$
  - $\alpha_i$ : repeatable characteristic of region  $i$
- Goal: predict  $\mu + \alpha_i$  for each region  $i$
- Best predictor is  $E \mu + \alpha_i | Y_i, \sigma_a^2, \sigma_e^2$
- Equation when both random variables have normal distributions,  $\mathbf{y}$  has multivariate normal distribution

$$\text{BLUP } \mu + \alpha_i = \hat{\mu} + (Y_i - \hat{\mu}) \frac{\sigma_a^2}{\sigma_a^2 + \sigma_e^2}$$

- When variances ( $\sigma_a^2$  and  $\sigma_e^2$ ) are estimated, more correctly called eBLUP (estimated BLUP)

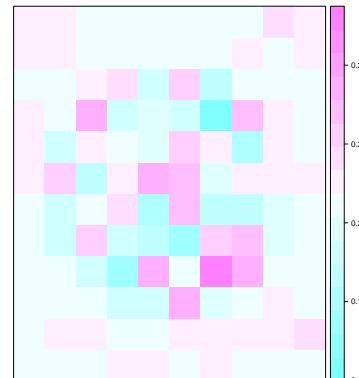
## Smoothing areal data using a mixed model

- Often called Fay-Herriot model when both random variables have normal distributions

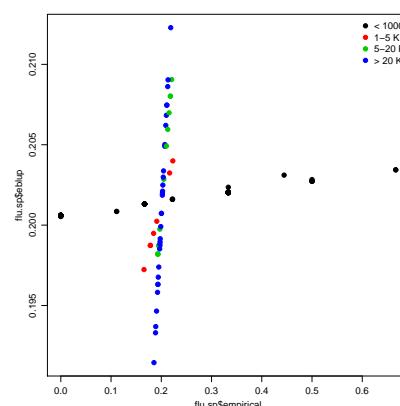
$$\text{BLUP } \mu + \alpha_i = \hat{\mu} + (Y_i - \hat{\mu}) \left( \frac{\sigma_a^2}{\sigma_a^2 + \sigma_e^2} \right)$$

- Behavior of the BLUP. Depends on  $\sigma_a^2$  relative to  $\sigma_e^2$
- Large "repeatable" variability,  $\sigma_a^2 >> \sigma_e^2$ :  $\frac{\sigma_a^2}{\sigma_a^2 + \sigma_e^2} \approx 1$ 
  - BLUP  $\mu + \alpha_i \approx Y_i$ .
  - No (or little) smoothing
- Large measurement error,  $\sigma_a^2 << \sigma_e^2$ :  $\frac{\sigma_a^2}{\sigma_a^2 + \sigma_e^2} \approx 0$ 
  - BLUP  $\mu + \alpha_i \approx \hat{\mu}$ .
  - extreme smoothing
  - Predictions are the estimated mean
- "Repeatable" variability usually assumed constant
- "Measurement error",  $\sigma_e^2$  may vary between areas
  - Areas get different amounts of smoothing
  - how much depends on the size of measurement error

## "Flu" data: Fay-Herriot smoothing



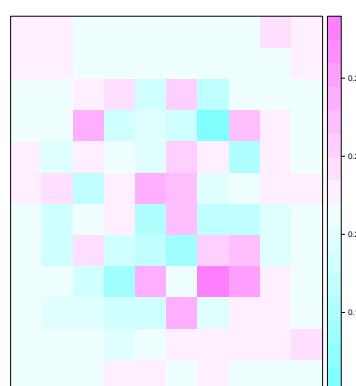
## "Flu" data: Fay-Herriot vs empirical



- Context: survey to estimate something in a large region
- e.g. Proportion of US adults who smoke more than 1 pack a month
  - Determine sample size based on desired precision of the estimated proportion
  - For the overall (all US, men + women, all ages) proportion
- Common to also report "small area" estimates
  - men-only, women-only, 20-24 year olds, 20-24 year old men, ...
  - Less precise because fewer responses for that subgroup
- But subgroups may be related
  - e.g. men/20-24 may be related to: women/20-24, men/25-30, ...

- Variability between sub-group-specific estimates has two components
  - Measurement error: what happens when different people in men/20-24 sample?
  - Variability in "true" proportion: repeatable characteristic of group
- We have a Fay-Herriot model
- When groups are very different:  $\sigma_a^2 \gg \sigma_e^2$ 
  - No, or little, smoothing
  - sub-group estimate is the observed value
  - little (or no) improvement in precision
- When groups are quite similar (or very imprecise):  $\sigma_a^2 \ll \sigma_e^2$ 
  - No repeatable variation between subgroups
  - Lots of smoothing
  - Sub-group estimate is close to the overall mean
  - Much more precise

- Previous smooth towards the global average
  - location  $i$  ignored
  - In the notation used below, the non-spatial FH model is  $\mathbf{y} = \mu + \mathbf{u} + \varepsilon$
  - What if you expect  $\mu_i$  to vary spatially?
    - The "repeatable" variation ( $\mathbf{u}$ ) is spatially correlated
    - The "measurement error" variation is independent
- $$\mathbf{y} = \mu + (\mathbf{I} - \mathbf{W})^{-1} \mathbf{u} + \varepsilon$$
- This is the spatial Fay-Herriot model
  - Uses a SAR model for the repeatable part (what's in software)
  - Requires specifying a spatial weight matrix
  - Same concept as measurement error kriging
  - $\varepsilon$  is the measurement error
- For flu data, very small spatial correlation  
so spatial and non-spatial FH give almost the same predictions



- There are many other approaches - all similar concept but different details
  - Bivand describes Marshall's local Empirical Bayes (EB) estimator
- When responses are counts or yes/no:
  - Distribution of  $y$  is not multivariate normal
  - No explicit formulae for smoothed predictions
  - Various approximations
  - Best approach is Bayesian
- And you can combine regression approaches with smoothing
  - Bivand has many details
  - Active research area.

## Summary of smoothing: Multivariate normal data

- one source of variability, spatially correlated
  - SAR (or CAR) on errors
$$\mathbf{y} = \mu + (\mathbf{I} - \mathbf{W})^{-1} \boldsymbol{\varepsilon}$$
  - Predictions averaged over neighboring residuals
  - Amount of smoothing depends on spatial correlation
- two sources of variability, no spatial correlation
  - Fay-Herriot model
$$\mathbf{y} = \mu + \mathbf{u} + \boldsymbol{\varepsilon}$$
  - Predictions are smoothed towards overall mean
  - Amount of smoothing depends on  $\sigma_a^2/\sigma_e^2$
- two sources of variability, with spatial correlation
  - Spatial Fay-Herriot model
$$\mathbf{y} = \mu + (\mathbf{I} - \mathbf{W})^{-1} \mathbf{u} + \boldsymbol{\varepsilon}$$
  - Predictions are smoothed towards local mean
  - How local depends on spatial correlation
  - Amount of smoothing depends on  $\sigma_a^2/\sigma_e^2$